# Classifier Evaluation

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- The errors committed by a classification model are generally divided into two types
	- **\*** Training errors
	- Generalization errors
- Training error is the number of misclassification errors committed on training records.
- Training error is also known as resubstitution error or apparent error.
- Generalization error is the expected error of the model on previously unseen records.

- A good classification model should
	- Fit the training data well. (low training error)
	- Accurately classify records it has never seen before. (low generalization error)
- A model that fits the training data too well can have a poor generalization error.
- This is known as model overfitting.

- We consider the 2-D data set in the following figure.
- The data set contains data points that belong to two different classes.
- 30% of the points are chosen for training, while the remaining 70% are used for testing.
- A decision tree classifier is applied to the training set.
- Different levels of pruning are applied to the tree to investigate the effect of overfitting



- The following figure shows the training and test error rates of the decision tree.
- Both error rates are large when the size of the tree is very small.
- This situation is known as model underfitting.
- Underfitting occurs because the model cannot learn the true structure of the data.
- It performs poorly on both the training and test sets.



- When the tree becomes too large
	- \* The training error rate continues to decrease.
	- \* However, the test error rate begins to increase.
- This phenomenon is known as model overfitting.

- The training error can be reduced by increasing the model complexity.
- However, the test error can be large because the model may accidentally fit some of the noise points in the training data.
- In other words, the performance of the model on the training set does not generalize well to the test examples.

- We consider a training and test set for a mammal classification problem.
- Two of the ten training records are mislabeled.
- Bats and whales are labeled as non- mammals instead of mammals.

# Training set



#### Test set



- A decision tree that perfectly fits the training data is shown in the following figure.
- The training error for the tree is zero.
- However, its error rate on the test set is 30%.



- Both humans and dolphins are misclassified as nonmammals.
- Their attribute values for Body Temperature, Gives Birth and Four-legged are identical to the mislabeled records in the training set.
- On the other hand, spiny anteater represents an exceptional case.
- The class label of the test record contradicts the class labels of other similar records in the training set.

- In contrast, the simpler decision tree in the following figure has
	- A somewhat higher training error rate (20%) but
	- \* A lower test error rate (10%).
- It can be seen that the Four-legged attribute test condition in the first model is spurious.
- It fits the mislabeled training records, which leads to the misclassification of records in the test set.



- Models that make their classification decisions based on a small number of training records are also susceptible to overfitting.
- We consider the five training records in the following table.
- The corresponding decision tree can label all the training records correctly.

# Training set





- Although the training error is zero, the error rate on the previous test set is 30%.
- The model classifies all warm-blooded vertebrates that do not hibernate as non- mammals.
- As a result, humans, elephants and dolphins are misclassified.
- This is because there is only one training record (eagle) with such characteristics.

#### Generalization error estimation

- The ideal classification model is the one that produces the lowest generalization error.
- The problem is that the model has no knowledge of the test set.
- It has access only to the training set.
- We consider two approaches to estimate the generalization error
	- \* Resubstitution estimate
	- Estimates incorporating model complexity
	- Using a validation set

### Resubstitution estimate

- The resubstitution estimate approach assumes that the training set is a good representation of the overall data.
- In other words, the training error can be used to provide an optimistic estimate for the generalization error.
- However, the training error is usually a poor estimate of generalization error.

### Resubstitution estimate

- We consider the two decision trees shown in the following figure.
- The left tree  $T<sub>L</sub>$  is more complex than the right tree  $T_R$ .
- The training error rate for  $T<sub>L</sub>$  is  $e(T<sub>L</sub>)=4/24=0.167$ .
- The training error rate for  $T_R$  is  $e(T_R)=6/24=0.25$ .
- Based on the resubstitution estimate,  $T<sub>L</sub>$  is considered better than  $T_R$ .

#### Resubstitution estimate



- The chance for model overfitting increases as the model becomes more complex.
- As a result, we should prefer simpler models.
- Based on this principle, we can estimate the generalization error as the sum of
	- **\*** Training error and
	- \* A penalty term for model complexity.

- In the case of a decision tree, let
	- **↓** *L* be the number of leaf nodes.
	- $\cdot$  *n<sub>l</sub>* be the *l*-th leaf node.
	- $\textbf{m}(n_l)$  be the number of training records classified by node  $n_l$ .
	- $\cdot$  *e*(*n<sub>l</sub>*) be the number of misclassified records by node *n<sub>l</sub>*.
	- $\langle \zeta(n_l) \rangle$  be a penalty term associated with the node  $n_l$ .
- The resulting error  $e_c$  of the decision tree can be estimated as follows:

$$
e_c = \frac{\sum_{l=1}^{L} [e(n_l) + \zeta(n_l)]}{\sum_{l=1}^{L} m(n_l)}
$$

- We consider the previous two decision trees  $T<sub>L</sub>$  and  $T_R$ .
- We assume that the penalty term is equal to 0.5 for each leaf node.
- The error estimate for  $T<sub>L</sub>$  is  $e_c(T_L) =$  $4 + 7 \times 0.5$ 24 =  $7.5$ 24  $= 0.3125$

• The error estimate for  $T_R$  is  $e_c(T_L) =$  $6 + 4 \times 0.5$ 24 = 8 24  $= 0.3333$ 

- Based on this penalty term,  $T<sub>I</sub>$  is better than  $T<sub>R</sub>$ .
- For a binary tree, a penalty term of 0.5 means that a node should always be expanded into its two child nodes if it improves the classification of at least one training record.
- This is because expanding a node, which is the same as adding 0.5 to the overall error, is less costly than committing one training error.

- Suppose the penalty term is equal to 1 for all the leaf nodes.
- The error estimate for  $T<sub>L</sub>$  becomes 0.458.
- The error estimate for  $T_R$  becomes 0.417.
- Based on this penalty term,  $T_R$  is better than  $T_I$ .
- A penalty term of 1 means that a node should not be expanded unless it reduces the misclassification error by more than one training record.

# Using a validation set

- In this approach, the original training data is divided into two smaller subsets.
- One of the subsets is used for training.
- The other, known as the validation set, is used for estimating the generalization error.

# Using a validation set

- This approach can be used in the case where the complexity of the model is determined by a parameter.
- We can adjust the parameter until the resulting model attains the lowest error on the validation set.
- This approach provides a better way for estimating how well the model performs on previously unseen records.
- However, less data is available for training.

#### Handling overfitting in decision tree

- There are two approaches for avoiding model overfitting in decision tree
	- Pre-pruning
	- Post-pruning

### Pre-pruning

- In this approach, the tree growing algorithm is halted before generating a fully grown tree that perfectly fits the training data.
- To do this, an alternative stopping condition could be used.
- For example, we can stop expanding a node when the observed gain in impurity measure falls below a certain threshold.

### Pre-pruning

- The advantage of this approach is that it avoids generating overly complex sub-trees that overfit the training data.
- However, it is difficult to choose the right threshold for early termination.
- A threshold which is too high will result in underfitted models.
- A threshold which is too low may not be sufficient to overcome the model overfitting problem.

### Post-pruning

- In this approach, the decision tree is initially grown to its maximum size.
- This is followed by a tree pruning step, which trims the fully grown tree.

## Post-pruning

- Trimming can be done by replacing a sub- tree with a new leaf node whose class label is determined from the majority class of records associated with the subtree.
- The tree pruning step terminates when no further improvement is observed.

### Post-pruning

- Post-pruning tends to give better results than prepruning because it makes pruning decisions based on a fully grown tree.
- On the other hand, pre-pruning can suffer from premature termination of the tree growing process.
- However, for post-pruning, the additional computations for growing the full tree may be wasted when some of the sub-trees are pruned.

# Classifier evaluation

- There are a number of methods to evaluate the performance of a classifier
	- Hold-out method
	- Cross validation
	- Bootstrap

### Hold-out method

- In this method, the original data set is partitioned into two disjoint sets.
- These are called the training set and test set respectively.
- The classification model is constructed from the training set.
- The performance of the model is evaluated using the test set.

### Hold-out method

- The hold-out method has a number of well known limitations.
- First, fewer examples are available for training.
- Second, the model may be highly dependent on the composition of the training and test sets.

### Hold-out method

- A training set which is too small may not be representative of the original data set.
- On the other hand, if the training set is too large, the estimated accuracy computed from the smaller test set is less reliable.

- In this approach, each record is used the same number of times for training, and exactly once for testing.
- To illustrate this method, suppose we partition the data into two equal-sized subsets.
- First, we choose one of the subsets for training and the other for testing.
- We then swap the roles of the subsets so that the previous training set becomes the test set, and vice versa.

- The estimated error is obtained by averaging the errors on the test sets for both runs.
- In this example, each record is used exactly once for training and once for testing.
- This approach is called a two-fold cross-validation.

- The k-fold cross validation method generalizes this approach by segmenting the data into k equal-sized partitions.
- During each run
	- One of the partitions is chosen for testing.
	- The rest of them are used for training.
- This procedure is repeated k times so that each partition is used for testing exactly once.
- The estimated error is obtained by averaging the errors on the test sets for all k runs.

- In the leave-one-out approach, each test set contains only one record.
- This approach has the advantage of utilizing as much data as possible for training.
- The drawback of this approach is that it is computationally expensive.
- Furthermore, since each test set contains only one record, the variance of the estimated error tends to be high.

#### Bootstrap

- In the bootstrap approach, the training records are sampled with replacement.
- If the original data has *R* records, a bootstrap sample of size *R* contains, on the average, about 63.2% of the records in the original data.
- This follows from the fact that the probability a record is chosen is 1-(1-1/*R*)*<sup>R</sup>*.
- When *R* is sufficiently large, the probability asymptotically approaches 1-*e*-1=0.632.

#### Bootstrap

- Records that are not included in the bootstrap sample become part of the test set.
- We construct a classification model from the bootstrap sample.
- The model is then applied to the test set to obtain an estimate of the accuracy  $a<sub>b</sub>$ .
- The sampling procedure is then repeated *B* times to generate B bootstrap samples.

#### Bootstrap

- One of the more widely used bootstrap sampling approaches is the .632 bootstrap.
- This approach first combines
	- $\cdot$  The accuracy of each bootstrap sample,  $a_{b}$ , with
	- The accuracy calculated from a training set that contains all the records,  $a_{\text{orig}}$
- The combined value is then averaged across all the different bootstrap samples to obtain the overall accuracy *aboot*

$$
a_{boot} = \frac{1}{B} \sum_{b=1}^{B} (0.632a_b + 0.368a_{orig})
$$